# A Self-Consistent Event Biasing Scheme for Statistical Enhancement

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- Motivation: faster convergence of the stochastic process;
  - Useful when rare events govern the transport process;
  - Population control versus Event biasing;
  - Splitting particles entering  $\Omega$  versus Guiding particles towards  $\Omega$  by biasing the classical transport probabilities;
- History: When proposed? Who is the Godfather of event biasing?
- Event Biasing: from frozen field to self-consistent algorithms;
- Simulation Results;

## **History: Statistical enhancement**

Particle splitting: Single Particle MC

• A. Phillips, P. Price," MC calculus of hot electron tails", Appl. Phys. Lett., 1977.

Event biasing in EMC: evolution problems, initial condition

- C. JACOBONI" Generalization of the Monte Carlo method for charge transport to BIASED simulations", *NASECODE VI*, Dublin, 1989.
- L. Rota, C. Jacoboni, and P. Poli, "Weighted EMC" Solid-St. Electron., 12, 1989.
- M. Nedjalkov, P. Vitanov," Iteration Approach.." Solid St. Electron, 10, 1989.
- F. Rossi, P. Poli, C. Jacoboni, "The Weighted..' Semicon. Sci. Technol., 7, 1992.

Single Particle MC:  $(\mathbf{k}, \mathbf{r})$  - stationary problem, boundary condition

- H. Kosina, M. Nedjalkov, S. Selberherr, "Variance Reduction...event biasing", *Proc. MSM 2001*
- H. Kosina, M. Nedjalkov, S. Selberherr, "The Stationary MC..- Part I and II", J. Appl. Phys., 93, 2003

### **Event Biasing: Concepts of MC integration**

Random variable  $\psi$ : takes values  $\psi(Q)$  with probability  $p_{\psi}(Q)$ .

$$E_{\psi} = \int dQ p_{\psi}(Q) \psi(Q) - \text{expectation value}$$

N realizations of  $p_{\psi} \rightarrow Q_1, \dots, Q_N$  sampling points

$$E_{\psi} \simeq \frac{1}{N} \sum_{i=1}^{N} \psi(Q_i) - \text{sample mean; Precision}(N, \sigma_{\psi})$$

#### **Evaluation of integrals:**

$$I = \int f(Q)dy = \int p(Q)\frac{f(Q)}{p(Q)}, \qquad (\psi = f/p = \psi(p))$$

Different  $\psi(p)$  - all have expectation value  $E_{\psi}=I$ , but different  $\sigma_{\psi}$ 

### **Event Biasing: Evaluation of integral equations**

$$f(Q) = \int dQ' f(Q') K(Q', Q) + f_0(Q)$$
 (1)

If the task is not f but  $\langle A \rangle = \int dQ A(Q) f(Q)$ 

Consider the adjoint to (1) equation:

$$g(Q') = \int dQ K(Q', Q) g(Q) + A(Q')$$
(2)

(1) is multiplied by g, (2) multiplied by f, integrated, compared:

$$\langle A \rangle = \int dQ A(Q) f(Q) = \int dQ f_0(Q') g(Q')$$

Iterative expansion:  $g(Q') = A(Q') + \sum_{n=1}^{\infty} \int dQ K^n(Q', Q) A(Q)$ 

Replace in  $\langle A \rangle = \int dQ f_0(Q') g(Q')$  - series:  $\langle A \rangle = \sum_i \langle A \rangle_i$ ;

$$\langle A \rangle_2 = \int dQ' dQ_1 dQ_2 P_0(Q') P(Q', Q_1) P(Q_1, Q_2) \frac{f_0(Q')}{P_0(Q')} \frac{K(Q', Q_1)}{P(Q', Q_1)} \frac{K(Q_1, Q_2)}{P(Q_1, Q_2)} A(Q_2)$$

Numerical trajectory: points  $Q_0 \to Q_1 \to Q_2$ , selected by  $P_0 \to P \to P$ .

The random variable  $\psi^{(2)}$  - product of weight  $W=\frac{f_0}{P_0}\frac{K}{P}\frac{K}{P}$  and A

$$N \text{ trajectories } (Q' \to Q_1 \to Q_2)_i \quad \to \quad \langle A \rangle_2 \simeq \frac{1}{N} \sum_i \psi_i^{(2)}$$

One  $\infty$  trajectory samples all terms  $\langle A \rangle = \sum_i \langle A \rangle_i$ ;

$$(Q' \to Q_1 \to Q_2 \to \ldots)_i \quad \to \quad \langle A \rangle_{\simeq} \frac{1}{N} \sum_i \psi_i$$

### **Event Biasing: Problem, initial and boundary conditions**

Task: evaluate mean value of physical quantity  ${\bf a}$  in domain  $\Omega$  at time  $\tau$   $A(Q)={\bf a}\theta_\Omega({\bf k},{\bf r})\delta(t-\tau)$ ,  $\theta_\Omega$  - domain indicator,  $Q=({\bf k},{\bf r},t)$ 

adjoint BE 
$$\rightarrow K(Q', Q) = S(\mathbf{k}', \mathbf{k}, \mathbf{r}) e^{-\int_{t'}^{t} \lambda(\mathbf{K}(y), \mathbf{R}(y)) dy} \theta_D(\mathbf{r}) \delta(\mathbf{r}' - \mathbf{r}) \theta(t - t')$$

 ${f K}(t), {f R}(t)$  - classical trajectory, independent on f,g - frozen field  $e^{-\int}$  and S if normalized give the natural probabilities for drift and scattering!

$$f_0(Q) = f_i(\mathbf{k}, \mathbf{r})e^{-\int_0^t \lambda(\mathbf{K}(y), \mathbf{R}(y))dy} + \int_0^t \mathbf{v}_{\perp}(\mathbf{k})f_b(\mathbf{k}, \mathbf{r}, t_b)e^{-\int_t^t \lambda(\mathbf{K}(y), \mathbf{R}(y))dy} dt_b$$

 $f_i$ ,  $f_b$  - initial and boundary conditions;  $\mathbf{v}_{\perp}(\mathbf{k})$  - inward normal velocity at boundary

### **Event Biasing: EMC and WEMC**

**EMC** is obtained by a particular choice of  $P_0$  and P:

- •Construct  $P_0^B$  from  $f_i$ ,  $f_b$  •Construct  $P^B$  from K:  $P = \lambda e^{-\int \lambda dy} \cdot \frac{S}{\lambda}$

Then 
$$W=1$$
 and  $\langle A \rangle = \sum_{n=1}^{N_{ au}} heta_{\Omega}(n) a_n$ 

 $N_{\tau}$  number of trajectories which at  $\tau$  belong to D;  $\theta_{\Omega}(n) = 1$  if the endpoint of the *n*-th trajectory is inside  $\Omega$  and 0 otherwise;  $a_n$  is the value of a for the n-th particle;

**WEMC-** all other choices of  $P_0$  and P:

Then 
$$\langle A \rangle = \sum_{n=1}^{N_{\tau}} W_n \theta_{\Omega}(n_{um}) a_n$$

 $\theta_{\Omega}(n_{um})=1$  if the n-th numerical particle is inside  $\Omega$  and 0 otherwise; Biased can be the initial  $f_i$ , boundary  $f_b$  distributions, free flight duration  $\lambda exp\{-\int \lambda dy\}$ , type of scattering and the selection of the after-scattering state direction  $S/\lambda$ .

### **Event biasing: self-consistent scheme**

Interacting carriers - Nonlinear problem. The frozen field approach fails. Solution - in the coupling scheme with the Poisson equation:

To proof the scheme (the idea : PE must not know about the secret life of the MC)

we must proof  $f_{ au}^{\mbox{b}} 
ightarrow f_{ au} 
ightarrow f_{ au}^{\mbox{b}}$ 

Main result: Particles weights survive the successive steps of solving the PE.

#### Simulation results

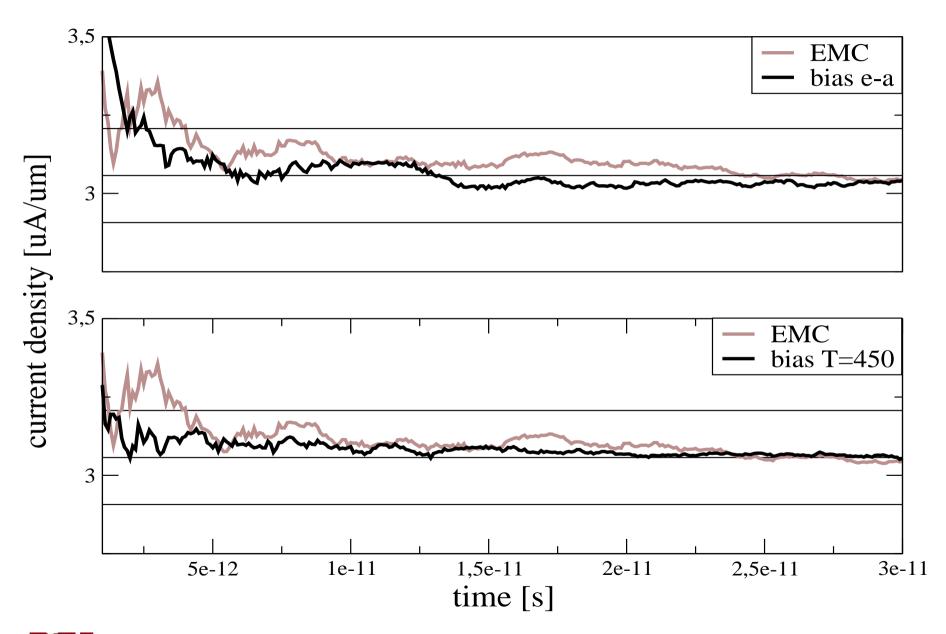
#### 2D MC, MOSFET:

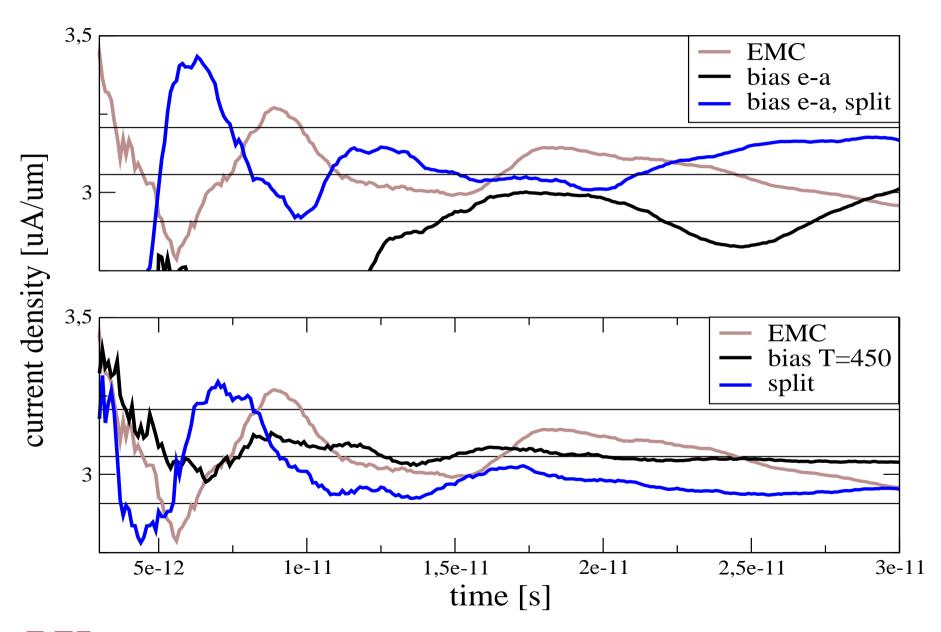
gate length 15nm, channel doping  $2.10^{19}cm^{-3}$ , and oxide thickness 0.8nm. Subthreshold regime  $V_G=0.375V$ ,  $V_D=0.1V$ , lattice temperature T=300K.

Consistency of the biasing techniques in the thermodynamic limit: for large N EMC and WEMC give the same distribution of the physical averages.

For smaller N we seek for bias processes with smaller variance.

Investigated is the convergence of the cumulative averages for the channel and terminal currents obtained from the velocity and particle counting respectively.





#### **Conclusions**

- Event biasing has been derived in presence of both, initial and boundary conditions and generalized for self-consistent simulations.
- A bias technique, particularly useful for small devices, is obtained by injection of hot carriers from the boundaries.
- $\bullet$  The coupling with PE requires a precise statistics in the S/D regions.
- Event biasing in combination with population control is necessary

 $f_0^b$  - from  $f_0/P_0$  - biasing of the initial/boundary distribution.

Decompose the phase space into cells  $\Omega_{l,m} = \Psi_l \Phi_m$ ,  $(\mathbf{r}_l, \mathbf{k}_m) \in \Omega_{l,m}$ :  $f_{\tau}^b \to f_{\tau}$ : directly from  $\langle A \rangle$  with a=1:

$$f_{l,m} \simeq \frac{\sum_{n} \theta_{\Omega_{l,m}(n)}}{V_{\Omega_{l}} V_{\Phi_{m}}} = \frac{\sum_{n} W_{n} \theta_{\Omega_{l,m}(n_{um})}}{V_{\Omega_{l}} V_{\Phi_{m}}}$$

Introduce distribution function of the numerical particles:

$$f_{l,m}^{\text{num}} \simeq \frac{\sum_{n} \theta_{\Omega_{l,m}(n_{um})}}{V_{\Omega_{l}} V_{\Phi_{m}}} \rightarrow f_{l,m} = W_{l,m} f_{l,m}^{\text{num}} \quad \text{if} \quad V_{\Omega_{l}}, V_{\Phi_{m}} \rightarrow 0$$

Hence  $W_{l,m} = f_{l,m}/f_{l,m}^{\text{num}}$  and  $f_{\tau} \to f_{\tau}^{\text{b}}$  follows with  $f_{\tau}^{\text{b}} = f^{\text{num}}$ .